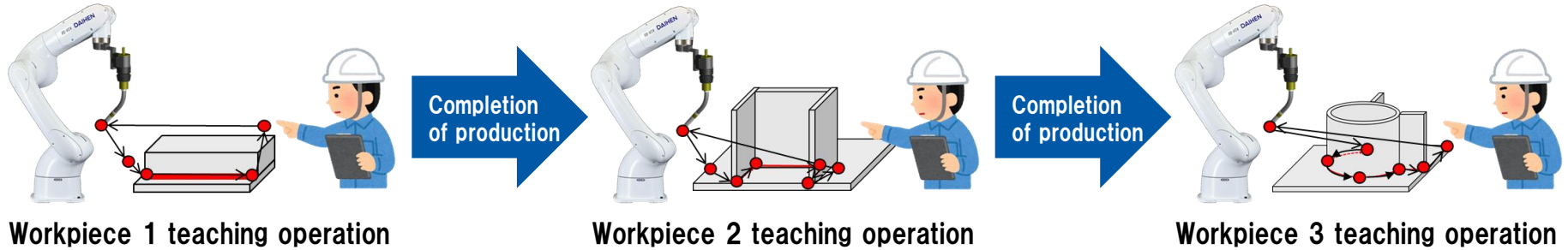




# New Proposal for High-mix, Low-volume Production in Which Robots “See” and Generate Their Own Movements

**Teaching-Less System**

Teaching work occurs frequently, so it is time consuming

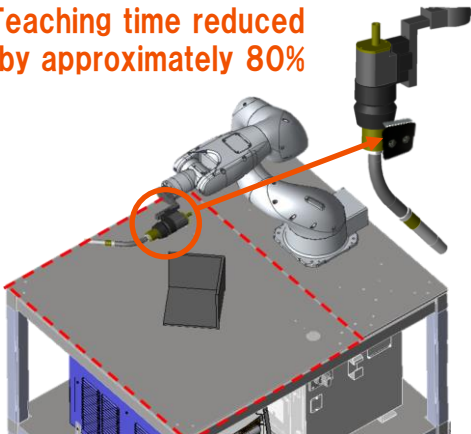


Especially for small products, teaching time is longer than production time

**DAIHEN's teaching-less system solves this trouble !**

Just place the workpiece and specify the welding location  
The robot “sees” the workpiece and automatically generates the motion!

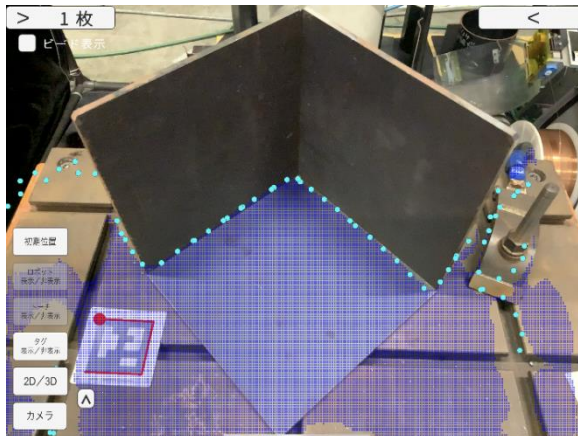
Teaching time reduced  
by approximately 80%



### ① Automation of shooting operation

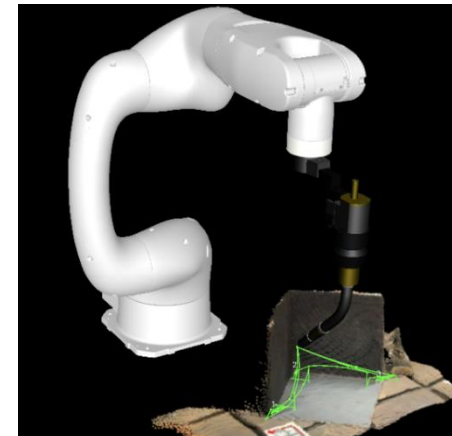
Workpiece recognition by photographing  
the entire workbench

Determine shooting position from  
workpiece position/orientation



### ② Weld line detection

The robot estimates and presents the  
welding location



### ③ Robot motion generation

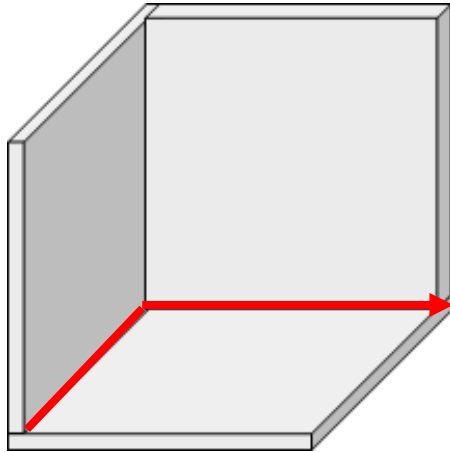
Automatically generates motion  
to avoid interference

**STEP1: Recognize the workpiece by shooting the entire platform**

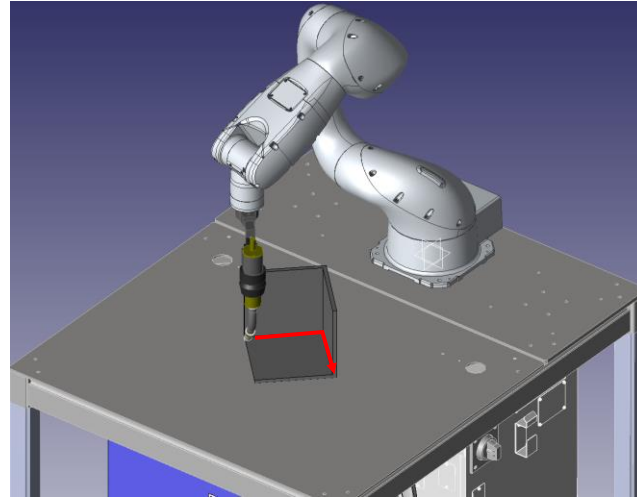
**STEP2: Determine the shooting position from the workpiece position posture and shoot**

**STEP3: Designate the part to be welded (human work)**

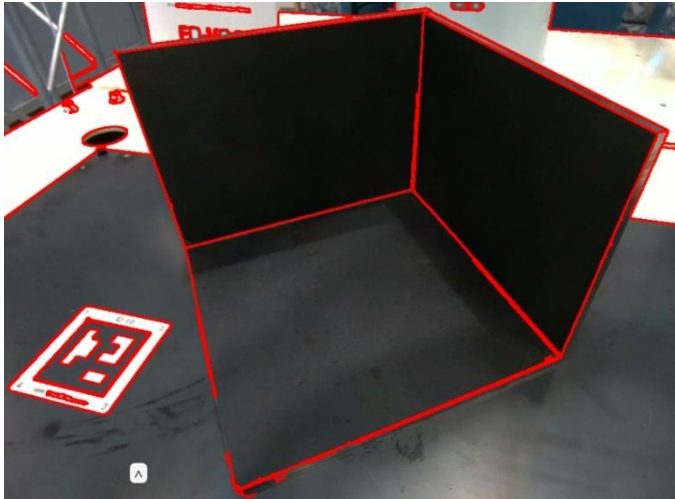
**STEP4: Robot motion generation and welding operations**



**Welded work**



## Automatic recognition of welding line candidates from workpiece shape



fillet joint



lap joint

**DAIHEN's teachingless system contributes to automation and productivity improvement in customer factories.**

**DAIHEN**